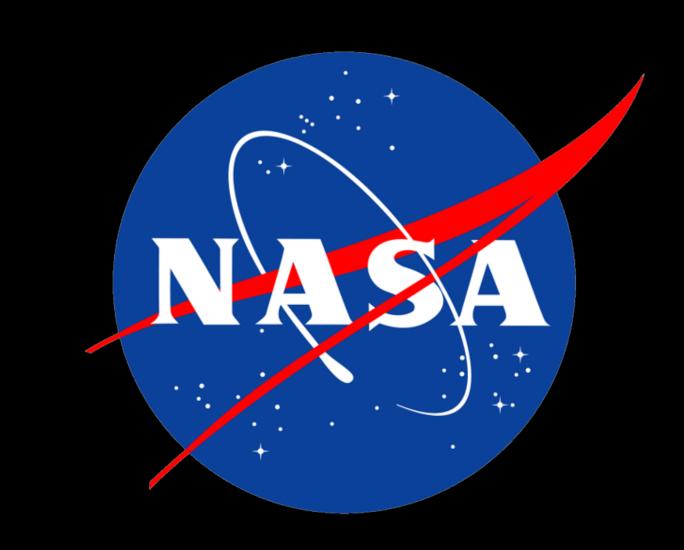


# Showcase and Comparison of Three Methods for Visualizing Near-Earth Satellite Conjunction Events



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#### Overview

- Conjunction assessment is a cornerstone of modern space safety
- Reliable visualization of the space environment can benefit operators and analysts alike
- Three new/extended methods provide more robust visualization of unusual conjunction geometries

#### Motivation

• Current conjunction visualization methods (Figure 1) fail when key probability of collision ( $P_c$ ) calculation assumptions are violated

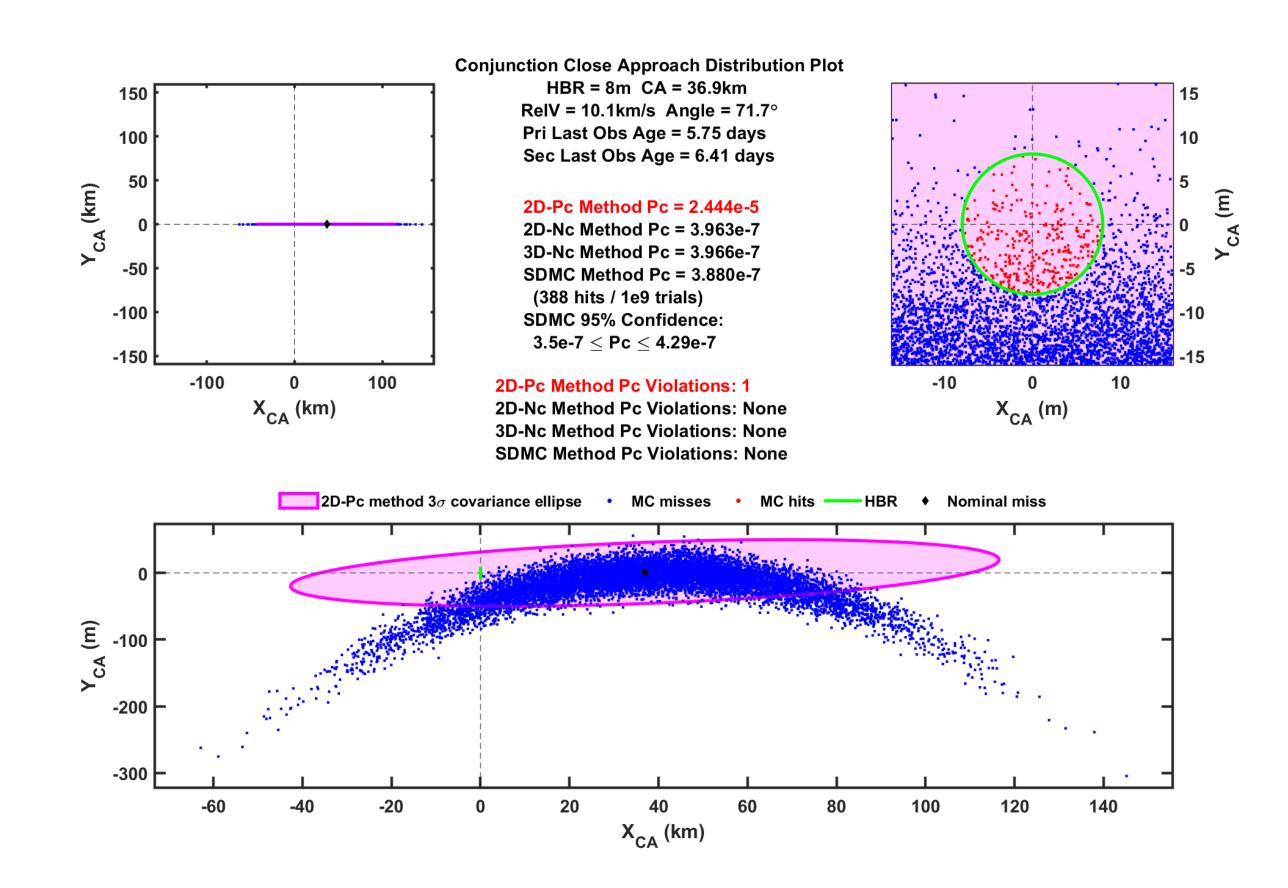


Figure 1. An example of a conjunction plane plot for a case in which it fails to accurately capture the conjunction environment.

### Methodology

- Implemented three visualization methods (ellipsoid, bananoid, and point cloud)
- Tested visualization methods against a variety of conjunction geometries to determine best and worst cases for a given method

## Results $P_c$ -2D: 2.44E-05 (METHOD VIOLATION) $N_c$ -2D: 3.96E-07 $N_c$ -3D: 3.97E-07 Peak Rate Time (+TCA): 2.324 s Combined HBR: 8.0 m $P_c$ -2D: 2.44E-05 (METHOD VIOLATION) $N_c$ -2D: 3.96E-07 $N_c$ -3D: 3.97E-07 Peak Rate Time (+TCA): 2.324 s Combined HBR: 8.0 m $P_c$ -2D: 2.44E-05 (METHOD VIOLATION) $N_c$ -2D: 3.96E-07 $N_c$ -3D: 3.97E-07 Peak Rate Time (+TCA): 2.324 s Combined HBR: 8.0 m

Figure 2. Illustrations of the ellipsoid (top), bananoid (middle), and point cloud (bottom) visualization methods for the conjunction illustrated in Figure 1, which includes a non-rectilinear pass and therefore fails  $2D-P_c$  and the ellipsoidal visualization.

#### **Method Details**

#### Ellipsoid

- Represents uncertainty distributions as shells corresponding to a desired n- $\sigma$  surface in Cartesian space
- Simple to derive and visualize from covariance matrices
- Applicable to typical conjunction geometries

#### Bananoid

- Represents uncertainty distributions as shells corresponding to a desired n- $\sigma$  surface in equinoctial space
- Moderately computationally intensive, but accurate for conjunctions where rectilinear assumptions are violated

#### Point Cloud

- Represents
  uncertainty
  distributions as a
  set of samples
  drawn directly
  from the
  underlying
  distribution in
  equinoctial space
- Computationally intensive, but free of underlying assumptions used in ellipsoid and bananoid methods

#### Conclusions

- The bananoid method is versatile and best suited to a wide variety of conjunction geometries
  - Effective for a wide range of relative velocities and clock angles, as well as for extended-duration conjunctions
- Direct visualization provides an advantageous understanding of the three-dimensional conjunction environment
- Visualization methods can accompany  $P_c$  calculations to improve understanding of conjunction events

#### **Future Work**

- Extension to cislunar and beyond conjunctions
  - Need new formulations that do not depend on equinoctial coordinates
  - New challenges associated with deep-space orbit determination
- Three-dimensional one-surface/one-cloud visualizations
  - Closer analog to CARA's current conjunction plane plots
  - Better parallels some calculations for determining  $P_c$